
EMBEDDED AUTOMATIC ROBOTIC VEHICLE NAVIGATION SYSTEM THROUGH SMS

ABSTRACT

The main aim of the project is to automate the robot navigation by using the wireless technology called GSM technology. So the robot can be controlled wirelessly without any hardwired connections.

A GSM modem provides the communication interface. It transports device protocols transparently over the network through a serial interface. A GSM modem is a wireless modem that works with a GSM wireless network. This GSM Modem can accept any GSM network operator SIM card and act just like a mobile phone with its own unique phone number. Advantage of using this modem will be that you can use its RS232 port to communicate and develop embedded applications. Applications like SMS Control, data transfer, remote control and logging can be developed easily. The modem can either be connected to PC serial port directly or to any microcontroller.

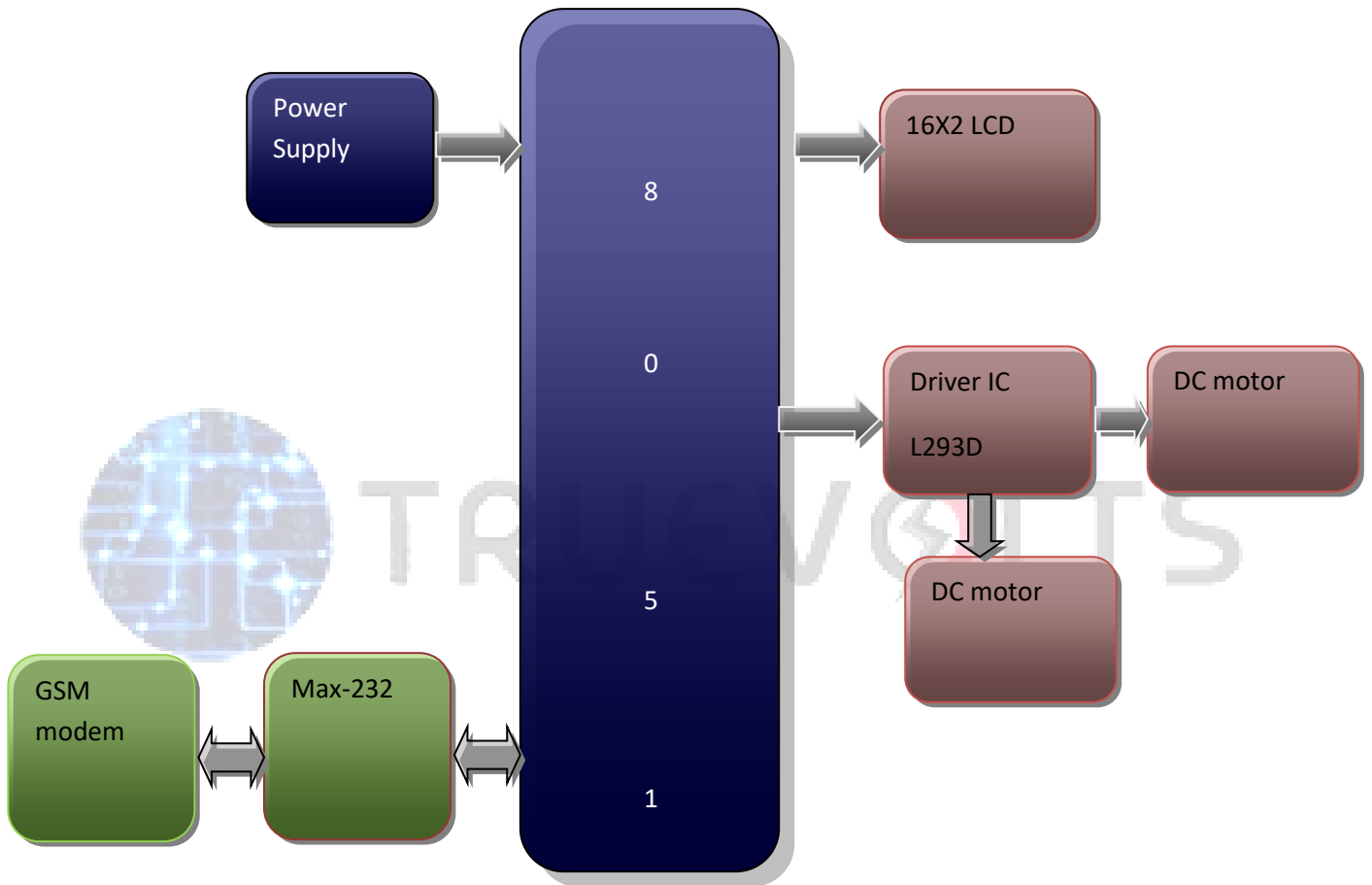
This project is designed in such a way that a GSM modem will be interfaced to the controller through serial port interface along with the to DC motors through voltage driver IC L293D. A model for robot will be designed by using these two motors. The microcontroller will be programmed in such a way that some predefined messages will be assigned to the controller for controlling the robot in different directions. When ever the user wants to control the navigation of the robot, he has to send predefined messages to the modem. When the modem receives data (SMS), it will intimate the same to the microcontroller. Now, it is the job of the controller performs the predefined task of controlling the robot in accordance with the message received from the modem. A 16X2 LCD will be interfaced to the controller to display the status of the robot.

This project uses regulated 5V, 500mA power supply. 7805 three terminal voltage regulator is used for voltage regulation. Full wave bridge rectifier is used to rectify the ac output of secondary of 230/12V step down transformer.

APPLICATIONS:

- Industrial applications
- Robotic applications

BLOCK DIAGRAM:



POWER SUPPLY BLOCKDIAGRAM:

